# The SHiP Spectrometer Straw Tracker CERN BDF and SHiP Workshop Berlin @Home

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#### Overview



- 1 The Spectrometer Straw Tracker
- 2 Straw Tubes
- 3 Tracker Stations
- 4 SST Mechanics and Designs UHH Design Prototype
- 5 Summary and Outlook



# Spectrometer Straw Tracker (SST)



- Reconstruct tracks of charged particles
  - Do tracks correspond to veto and timing detector hits?
  - Do tracks have a common vertex?
  - Does the mother particle point back to the target?



#### Aims/Requirements

- $\bullet$  Spatial hit resolution of  $120\,\mu m$
- Hit efficiency > 99%
- Operated in vacuum
- Minimize multiple scattering



### Straw Tubes



# Suitable technique

- Ultra-light straw drift detectors
- Straw tubes based on NA62 design with increased length and radius
- Welded Mylar (BoPET) foil
- Produced by JINR Dubna

Wall thickness 36 µm

Coating Au (20 nm), Co (50 nm)

 $\begin{array}{cc} {\rm Diameter} & 2\,{\rm cm} \\ {\rm Length} & 5\,{\rm m} \end{array}$ 

Operated with Ar/CO<sub>2</sub> @1 bar

 Shorter tube tested in 2017 testbeam: CERN-SHiP-INT-2019-005





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- ullet Operated with Ar/CO<sub>2</sub> @1 bar
- Shorter tube tested in 2017 testbeam: CERN-SHiP-INT-2019-005

#### But adding more challenges . . .

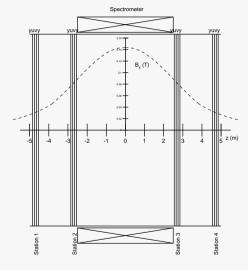
- Handling of straws
- Flowing of Mylar
- Increase of sagging over time
- Dynamic forces on support frame over time (bending)





# SST Layout





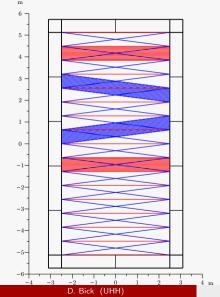
- Located at the end inside the vacuum vessel
- $\bullet$  Aperture:  $5 \, \text{m} \times 10 \, \text{m}$ 
  - width constrained by spatial distribution of muon background
- Large dipole magnet
  - $B_{\rm max} \simeq 0.14\,{\rm T}$  in x-direction
  - Field integral 0.65 Tm
- A pair of tracking stations on each side
- ullet 4 views per station:  $y\ u\ v\ y$

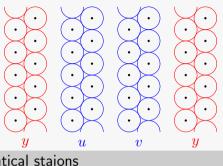


# Station Design



6 / 24





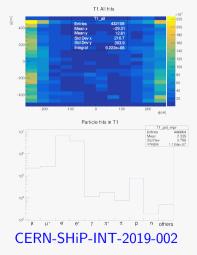
### Four identical staions

- ullet Each station has four views:  $y\ u\ v\ y$
- ullet y-views: horizontal straws of 5 m length
- ullet u- and v-views are rotated by a stereo angle  $\sim$  5 $^{\circ}$
- 2 layers per view (depending on final design)
- 16 000 straws altogether



#### Hit Rates from Simulation





T4 All hits

T5 all hits

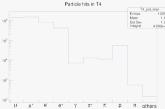
T5 all hits

T6 all hits

T6 all hits

T6 all hits

T7 al



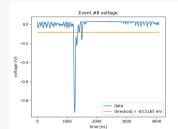
 $\circ$   $\mathcal{O}(10^7)$  hits/station/second

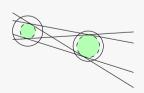
	Max. Rate	Avg. Rate
	kHz/Tube	kHz/Tube
T1	6.68	3.88
T2	1.09	0.63
Т3	1.97	1.05
T4	1.77	1.07



# Straw Tube Signals







- $\bullet$  Triggerless readout  $\to$  all signal are sent to DAQ
- Offline matching of hits
- ullet Time between  $t_0$  (e.g. from timing detector) and start of signal: drift time
- ⇒ corresponds to drift distance

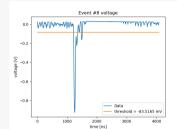
#### Precise measurement of $t_0$

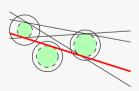
- $\bullet$  Chip development by FZJ  $\rightarrow$  see D. Arutinov's talk
- Under investigation: possibility to also use
  - Time over threshold
  - Total charge
  - (Part of the) waveform



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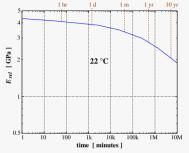
# Mechanical Challenges



### Main mechanical challenge:

#### Flowing of Mylar

- Reduction of tension to half over 10 years SHiP-INT-2018-001
- Additional forces when vessel is evacuated and straws are under pressure



#### **Implications**

- Reduced tensions increase gravitational sagging of the straws over time
  - ⇒ changing the eccentricity of the wire
  - ⇒ electrostatic deflections!
- Reduced tensions relax load on any supporting frame, which would thus unbend
- An unbending frame pulls on the wire, which would thus rupture ( $\Delta \ell_{\sf max} \simeq 10\,{\sf mm}$ )



#### SST Station Mechanics



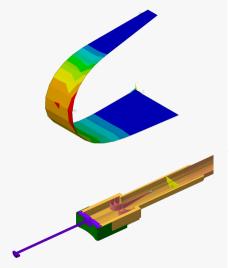
# Three alternative designs

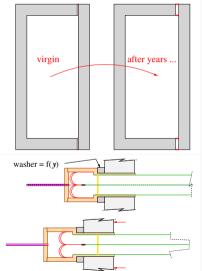
- 1) Constant force springs and adjusted pulling
  - Decouple tension of the wire form the straws
  - Increase pulling on the straws over time to compensate for relaxation
- 2 Cemented pack
  - Glue straws together for self-support, thus reducing sagging (boost bending stiffness)
  - No external traction on straws, only overpressure
  - Increase of length due to Mylar creeping within elastic region of the wire
- 3 Suspended bridge design
  - ullet Very stiff frame to minimize unbending when Mylar relaxes o wire is safe
  - Additional carbon fibers to suspend straws, thus defining the sagging

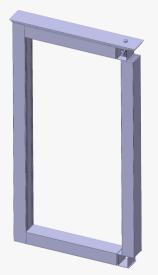


# Constant Force Springs + Expandable Frame











#### Cemented Pack

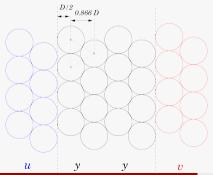


#### Single straw

#### Two cemented straws







- Based on PANDA idea
- Straws are glued together for stabilization
- 64 or more straws on top in a a pack form a module
- Only lightweight support structure needed,
   no external traction and thus no forces on frame
- Started to produce small scale (short) prototype



# Traction and Elongation



# Allowed range of the 5 m wire

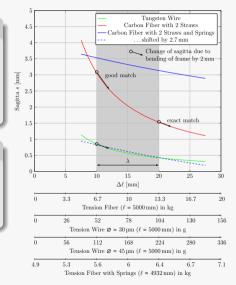
- $\bullet$  for a minimum traction to avoid electrostatic deflections  $\Delta\ell_{\rm min}=10\,{\rm mm}$
- ullet elastic limit  $\Delta\ell_{\sf max} = 20\,{\sf mm}$
- ullet corresponding sagitta s between 1 mm and 0.5 mm

#### Straw

- $\bullet$  for  $s=1\,\mathrm{mm},$  straw must be pulled with  $10\,\mathrm{kg}$
- this increases to 2 mm when tension halves
- frame unbends and pulls further on wire

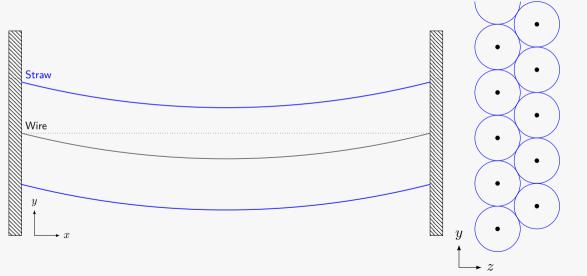
Solution: define sagging of straw by a carbon fiber

One fiber supports two straws



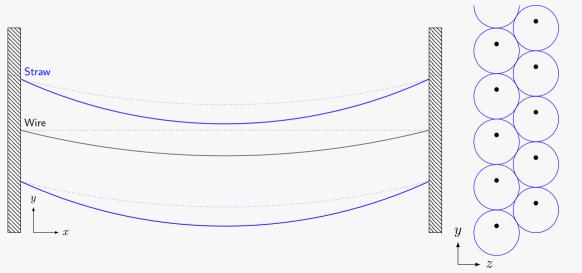






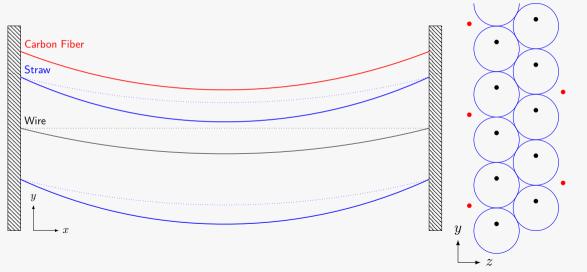






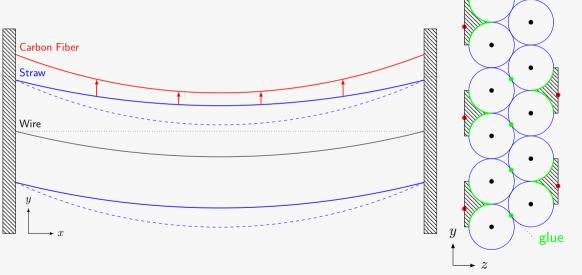










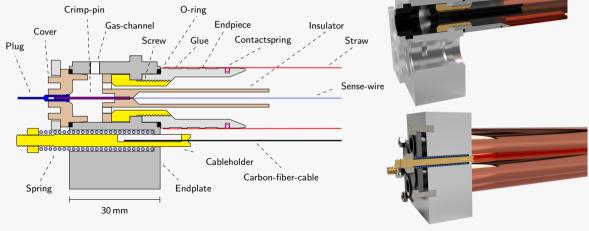




### Concept End-Plate



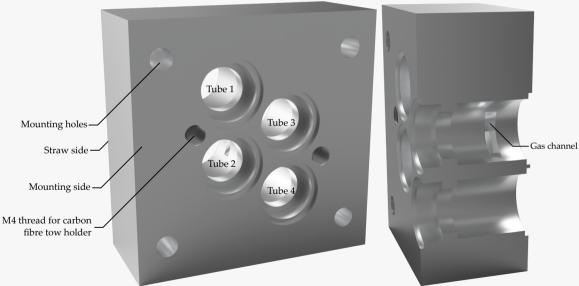
# Based on OPERA Experience





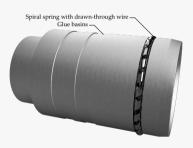
#### The End Plate

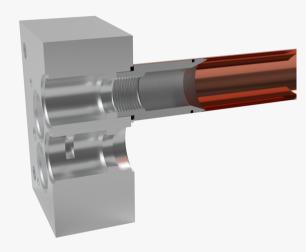






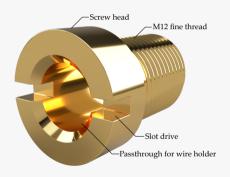


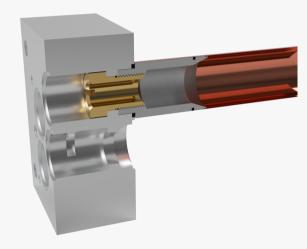






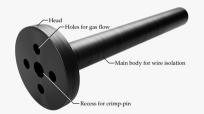


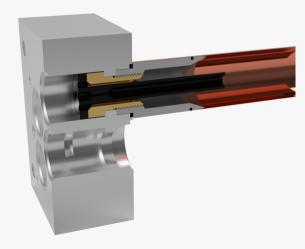








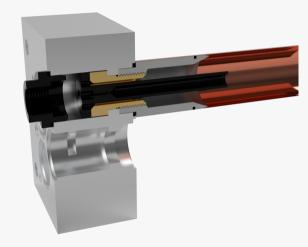






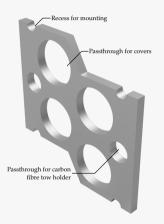


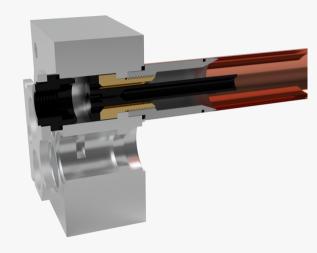








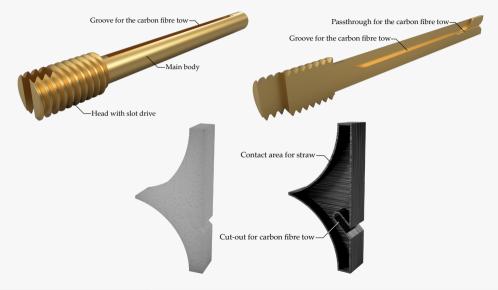






### Adding the Suspension



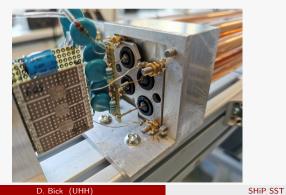




# Prototype with Four Tubes







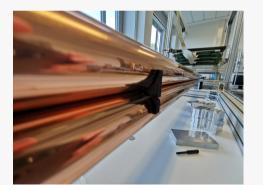




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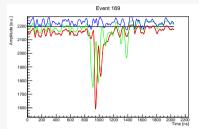


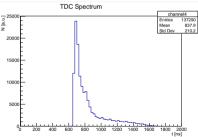




# First Functionality







- Two different wire diameters (30 μm and 45 μm)
- Separate HV supply
- Signal amplified by L3 amplifier (used in OPERA)
- Signal readout by multi channel FADC
  - Auto trigger
  - External trigger (scintillators)
- Reference detector (former OPERA test modules)

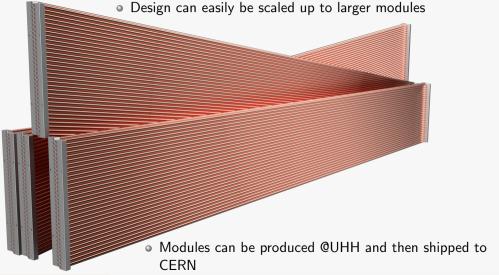
#### Future Steps

- Intensive testing with prototype
  - HV, wire diameters, gas, attenuation, . . .
- Study impacts of varying tensions etc.
- Will include a spring to reduce nervousness



# Modular Design

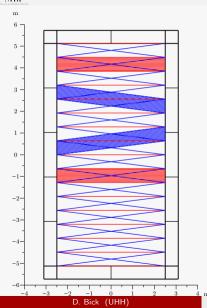






# Station Design





- Modules for a stack of  $32 \times 2$  tube in a view
- Stereo views: shift by one module height over the width
- Module can be mounted from the side into a frame

Active height	$10.25\mathrm{m}$
Active widths	$5.0\mathrm{m}$
Module height	$64\mathrm{cm}$
Straws per module	64
Sequence of 4 stereo views	y- $u$ - $v$ - $y$
Stereo angle	$127 \mathrm{mrad} = 7.3^{\circ}$
Horizontal modules per view	16
Stereo modules per view	15
Straws per station	3968
Total number of straws	15872



### Summary and Outlook



- Technology well suited but mechanics challenging
- Vivid R&D ongoing
- Alternative designs under study
  - converge to one design for TDR
- Working prototype @UHH
  - Concept based on well established technology from NA62 and OPERA
  - First ever working 5 m long prototype now operating in our lab
  - Concept documented in CERN-SHiP-INT-2019-006
  - Next step: design of a 64 strawtube module
- ullet Rough design for a frame exists (more a proof of concept) o further work needed



#### **SST Institutes**



